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(radians per unit of time squared) and angular momentum (moment of inertia times unit of angular velocity). Very often, objects exhibit linear and rotational motion.

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numerically. As a consequence, most of the analytical exercises and homework found in traditional dynamics texts written at this level are replaced by MATLAB®-based simulations. Second, extensive use is made of matrices. Matrices are essential to define the important role

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that constraints have on the behavior of dynamical systems. Matrices are also key elements in many of the software tools that engineers use to solve more complex and practical dynamics problems, such as in the multi-body codes used for analyzing mechanical, aerospace, and

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conventional dynamics and the highly specialised and distinctive approach used in robotics. The text finishes with an excursion into the Special Theory of Relativity mainly to define the boundaries of Newtonian Dynamics but also to re-appraise the fundamental definitions. Through its

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